

14. Partial differential equations

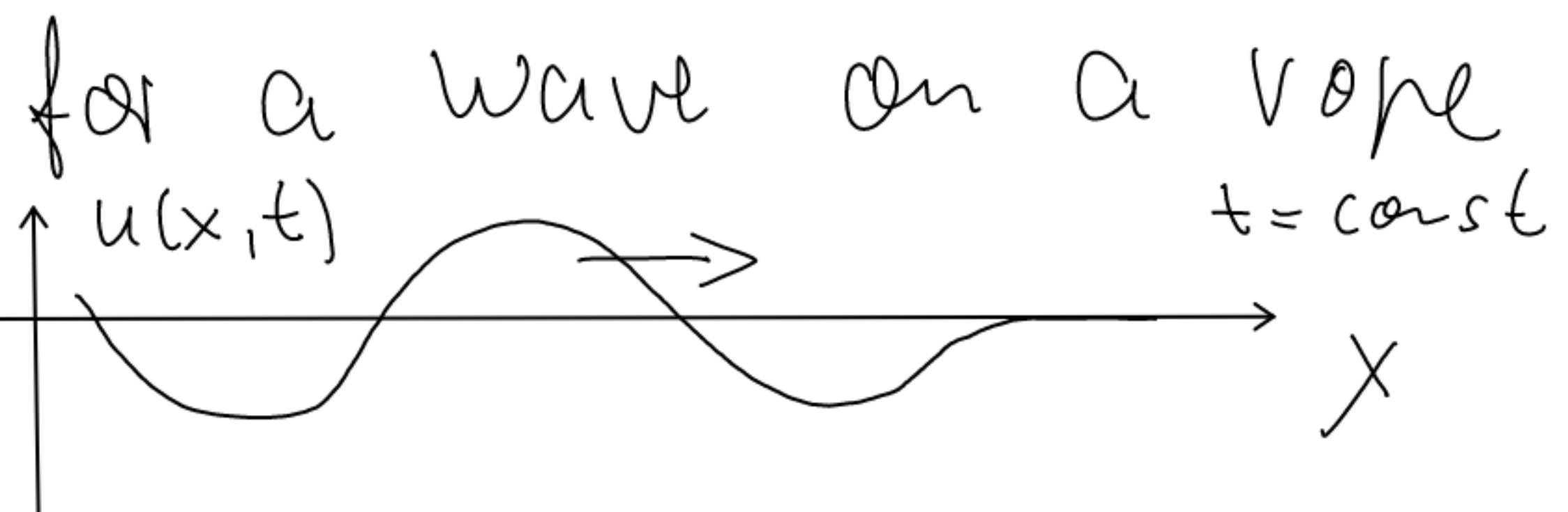
examples: 1) Poisson equation (elliptic)

$$\Delta \phi = -\rho(\vec{r}) \quad \text{for the potential } \phi(\vec{r}) \text{ sourced}$$

→ boundary conditions (BCs) by a charge distribution $\rho(\vec{r})$

2) wave equation (hyperbolic)

$$\frac{\partial}{\partial t} - \partial_t^2 U = v^2 \partial_x^2 U$$



→ BCs and initial and initial condition

3a) diffusion equation (parabolic)

$$\partial_t C = D \partial_x^2 C \quad \text{for a concentration } C(x,t)$$

3b) Schrödinger equation ✓ (:-)

$$\text{with } \partial_t \psi = \hat{H} \psi \quad \text{for the wave function } \psi(x,t)$$

→ complex diffusion coefficient of a particle

General trick: Discretize time and space points on multi dimensional lattice?

6.1. Poisson equation

example in 2 dimensions:

$$\Delta \phi = \partial_x^2 \phi + \partial_y^2 \phi = -\rho(x,y)$$

boundary conditions:

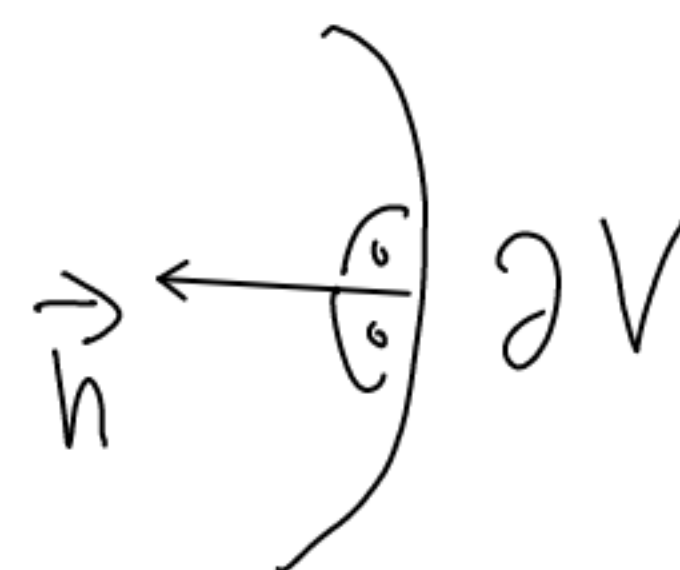


$$\phi|_{\partial V} = \phi_D \quad \text{Dirichlet bc}$$

$$\nabla_{\vec{n}} \phi|_{\partial V} = \phi_N \quad \text{Neumann bc}$$

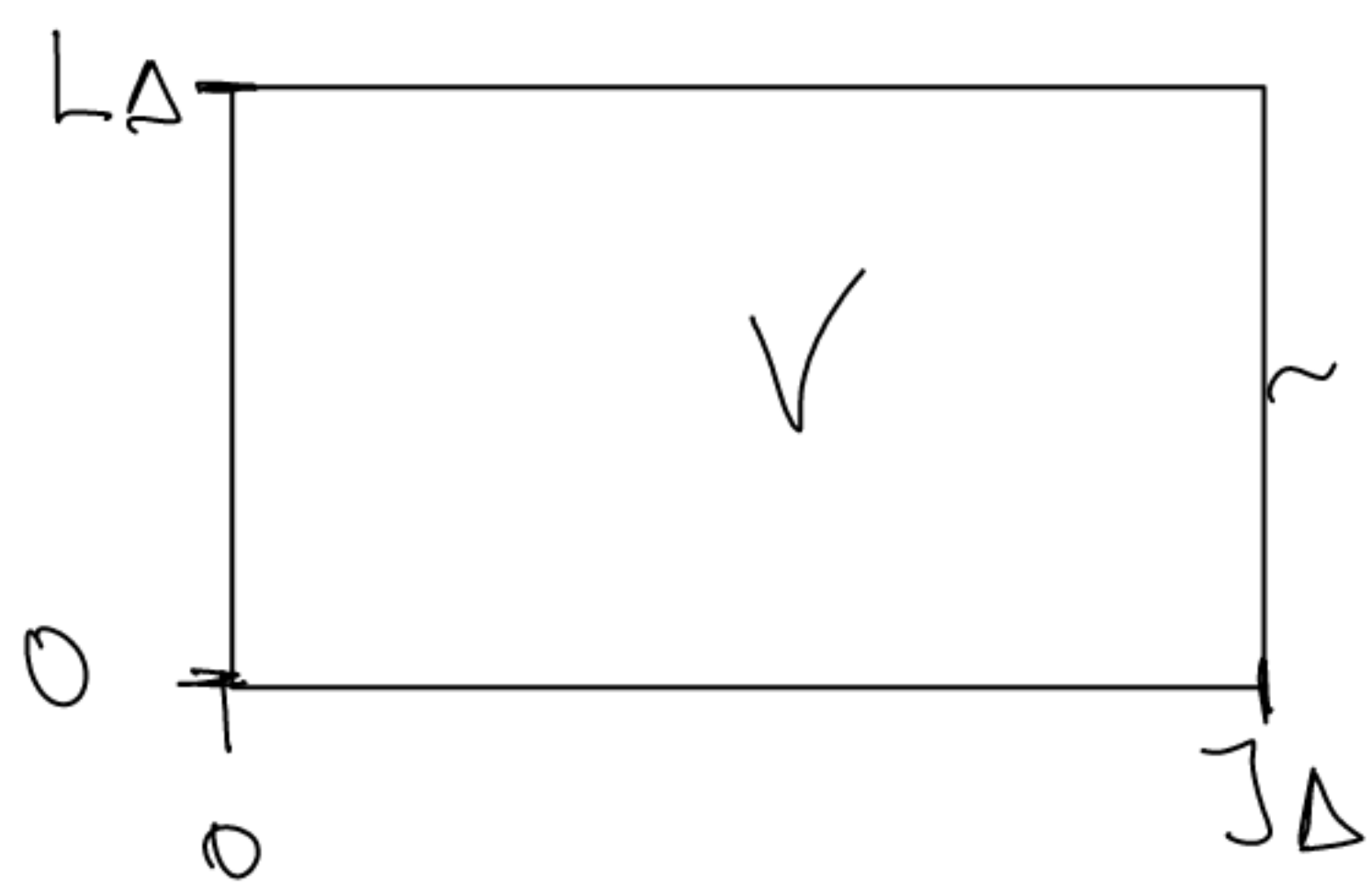
$\nabla_{\vec{n}}$ = directional derivative orthogonal to boundary

for $|\vec{n}|=1$ $\nabla_{\vec{n}} = \vec{n} \cdot \vec{\nabla}$



discretization like before $\phi(x,y) \rightarrow \phi_{j,e} = \phi(j\Delta, l\Delta)$
 $g(x,y) \rightarrow g_{j,e} = g(\dots)$

simple V is a rectangle $\Rightarrow V$ has $j=1, \dots, J-1$ and $l=1, \dots, L-1$



while ∂V is given by

$j=0, j=J, l=0, \text{ or } l=L$

with Dirichlet bc $\phi|_{\partial V} = 0$

$$\partial_x^2 \phi + \partial_y^2 \phi \approx \frac{\phi_{j+1,e} - 2\phi_{j,e} + \phi_{j-1,e}}{\Delta^2} + \frac{\phi_{j,e+1} - 2\phi_{j,e} + \phi_{j,e-1}}{\Delta^2} = -g_{j,e}$$

Linear system! How to solve?

1-dim version $\frac{\phi_{i-1} - 2\phi_i + \phi_{i+1}}{\Delta^2} = -P_i$ (1)

with bc. $\phi_0 = \phi_l$ and $\phi_N = \phi_r$ $i=0, \dots, N$

$A \cdot \vec{\phi} = \vec{r}$

for $A = \frac{1}{\Delta^2} \begin{pmatrix} -2 & 1 & & & 0 \\ 1 & -2 & 1 & & \\ & 1 & -2 & 1 & \\ & & 1 & -2 & 1 \\ 0 & & & 1 & -2 \end{pmatrix}$ and

$\vec{\phi}^T = (\phi_1, \dots, \phi_{N-1})$

source bc. $\vec{r} = - \begin{pmatrix} g_1 \\ \vdots \\ g_{N-1} \end{pmatrix} - \frac{1}{\Delta^2} \begin{pmatrix} \phi_l \\ \vdots \\ \phi_r \end{pmatrix}$

solved by QR-iteration (\rightarrow 8.3) or Jacobi-Iteration

$\left(\begin{array}{c} \text{---} \\ \Sigma \\ \text{---} \\ c \end{array} \right)$ 1) Write (1) as fixed point equation,

$$\vec{\Phi} = F(\vec{\Phi}), \quad \boxed{\phi_i = \frac{1}{2} (\phi_{i-1} + \phi_{i+1}) + \frac{1}{2} \Delta^2 S_i}$$

2) Guess initial value $\vec{\Phi}^{(0)}$ and iterate

$$\vec{\Phi}^{(i+1)} = F(\vec{\Phi}^{(i)})$$

remember Banach fixed point theorem, F is contraction
 \rightarrow always converges $(:-)$ \rightarrow check

$$|\vec{\Phi}^{(i+1)} - \vec{\Phi}^{(i)}| < \epsilon \quad \text{the stop iteration}$$

remark: similar work Gauß-Seidel iteration and

relaxation method.

In 2-dim. $\left(\begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \end{array} \right)$

$$\boxed{\phi_{j,e}^{(n+1)} = \frac{1}{4} (\phi_{j+1,e}^{(n)} + \phi_{j-1,e}^{(n)} + \phi_{j,e+1}^{(n)} + \phi_{j,e-1}^{(n)}) + \frac{1}{4} \Delta^2 S_{j,e}}$$

6.2. Wave equation

is a special form of the continuity equation

$$\boxed{\partial_t \vec{u} = -\partial_x \vec{j}(\vec{u})} \quad \text{with the current (density) } \vec{j}(\vec{u})$$

take now $\vec{u} = \begin{pmatrix} E \\ B \end{pmatrix}$ and $\vec{j} = -v \begin{pmatrix} B \\ E \end{pmatrix}$ to get

$$\left. \begin{aligned} \partial_t E &= -v \partial_x B \\ \partial_t^2 E &= -v \partial_x \partial_t B = v^2 \partial_x^2 E \end{aligned} \right\} \begin{array}{l} 1+1\text{-dim.} \\ \text{ED} \end{array}$$

⇒ we rather solve

$$\partial_t u = -v \partial_x u$$

for

remember 2nd order → 2x 1st order

$$u_j^n = u(j \Delta x, n \Delta t)$$

after discretization:

$$\frac{u_j^{n+1} - u_j^n}{\Delta t} = - \frac{j(u_{j+1}^n) - j(u_{j-1}^n)}{2 \Delta x} = -v \frac{u_{j+1}^n - u_{j-1}^n}{2 \Delta x}$$

$$\Rightarrow u_j^{n+1} = u_j^n - \frac{v \Delta t}{2 \Delta x} (u_{j+1}^n - u_{j-1}^n)$$

forward in time, centered in space (FTCS-scheme)

explicit method, similar to Euler's method

BUT unstable, errors magnify over time

Better is the Lax scheme

$$u_j^{n+1} = \frac{1}{2} (u_{j+1}^n + u_{j-1}^n) - \frac{v \Delta t}{2 \Delta x} (u_{j+1}^n - u_{j-1}^n)$$

which is stable for $\frac{v \cdot \Delta t}{\Delta x} < 1$

6.3. Diffusion equation

Continuity equation with $j(u) = -D \partial_x u$ diffusion const.

For $\frac{2D \Delta t}{\Delta x^2} < 1$, already FTCS-scheme is stable.