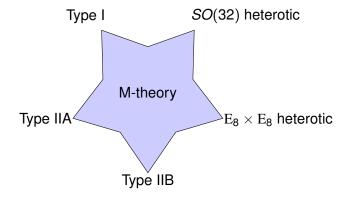
Consistent Truncations and Dualities

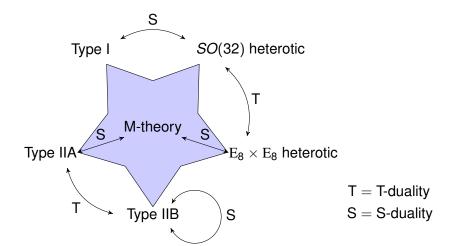
Falk Hassler

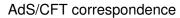
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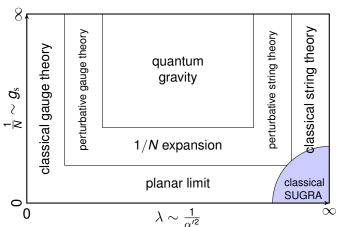


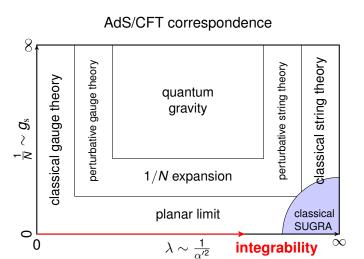
February 15th, 2020









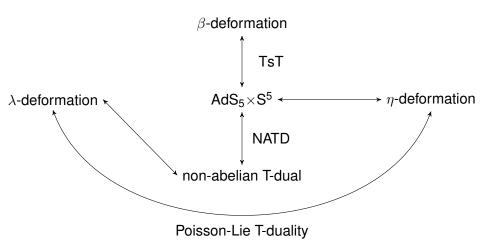


 λ -deformation

 β -deformation

 $AdS_5 \times S^5$

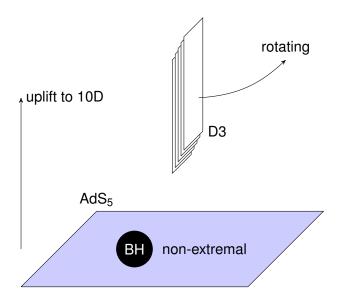
 η -deformation



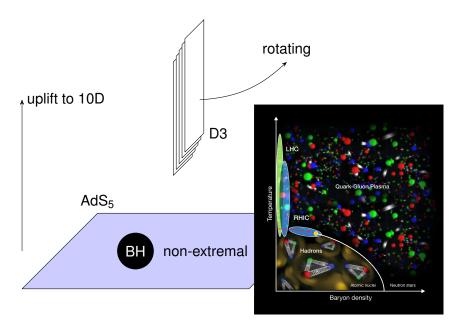
Motivation: Dualities and consistent truncations



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Motivation: Dualities and consistent truncations



Outline

1. Motivation

2. Consistent truncations

3. Poisson-Lie T-duality

4. Outlook

Consistent truncations

- What are consistent truncations of SUGRA?
- Why are they useful?
- ▶ How are they related to Poisson-Lie T-duality?

Motivation: 1-loop quantum corrections

•
$$\sigma$$
-model $S = \frac{1}{2} \int d^2 \sigma \sqrt{-h} \left[h^{\mu\nu} \partial_{\mu} X^i (G_{ij} + B_{ij}) \partial_{\nu} X^j + \phi R^{(2)} \right]$ is renormalizable

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- \triangleright β -functions match the field equations of the target space action

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m d}^d x\, \sqrt{-G}e^{-2\phi}ig(R^{(d)}+4\partial_i\phi\partial^i\phi-rac{1}{12}H_{ijk}H^{ijk}ig)$$
 with $H_{iik}=3\partial_{[i}B_{ik]}$

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- > symmetries:
 - 1. diffeomorphisms: $\delta G = L_x G$ $\delta B = L_x B$
 - 2. *B*-field gauge transformation: $B \rightarrow B d\phi$
- both captured by generalized Lie derivative

$$\delta \mathcal{H} = \mathcal{L}_{\left(oldsymbol{x} \mid \phi
ight)} \mathcal{H}$$

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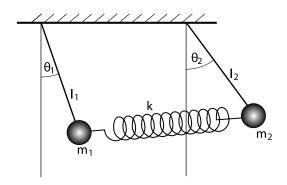
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 - 4. ...
- a prominent idea: reduce dimensions
- get ride of some degrees of freedom
- → simpler to find solution

New challenge: find consistent truncations

- 1. consistent ansatz for fields in 10/11D
- 2. reduce action with this ansatz
- 3. solve field equations of reduced action
- uplift solution

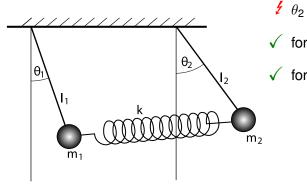
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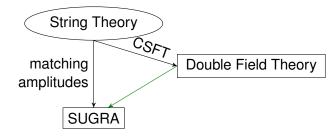


$$f \theta_2 = 0$$

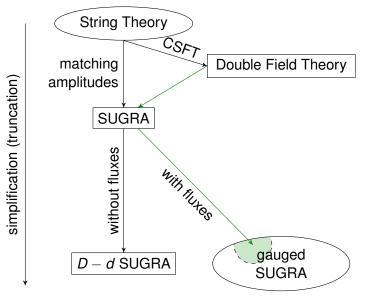
$$\checkmark$$
 for $m_2 \to \infty$ set $\theta_2 = 0$

$$\checkmark$$
 for $m_1=m_2$ set $\theta_1=\theta_2$

[Aldazabal, Baron, Marques, and Nunez, 2011, Geissbuhler, 2011]



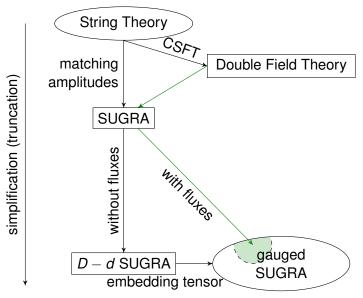
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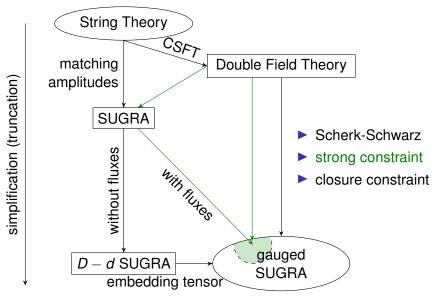
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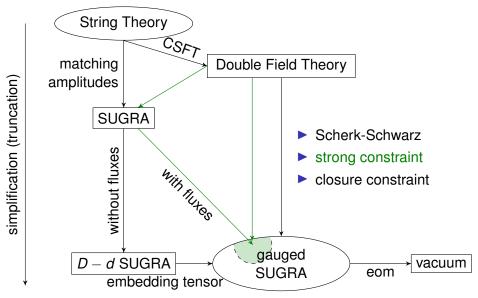
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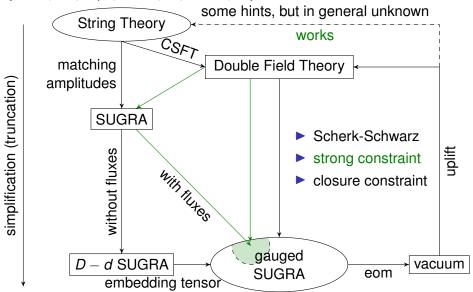
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Motivation

Consistent truncations

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- 2. frame algebra

$$\mathcal{L}_{E_A}E_{B}{}^{I}=F_{AB}{}^{C}E_{C}{}^{I}$$

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- ▶ $F_{AB}{}^{C}$ is the embedding tensor; embeds gauge group $G \hookrightarrow O(d,d)$
- ansatz is consistent
- remaining challenge:

find one E_A (unique?) for each F_{AB}^{C}

The solution

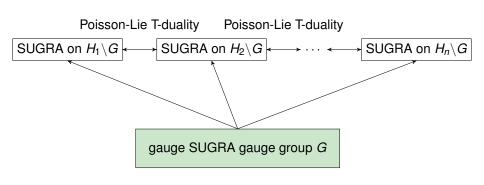
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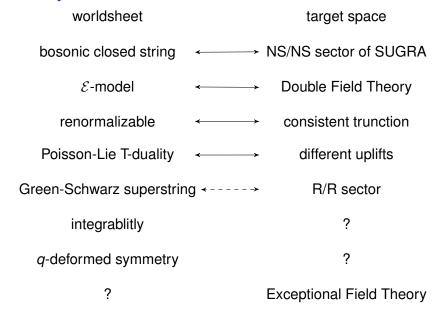
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Dictionary



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- TODO: explicit construction

Poisson-Lie T-duality

- What is Poisson-Lie T-duality?
- How does it connects to consistent truncations?

Two-dimensional σ -model: Lagrangian and Hamiltonian

$$lacksquare$$
 action $S=rac{1}{2}\int \mathrm{d}^2\sigma \sqrt{-h}h^{\mu
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$$\Pi_i = \textit{G}_{ij}\partial_{\tau}\textit{X}^j + \textit{B}_{ij}\partial_{\sigma}\textit{X}^j$$

to write

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with the Hamiltonian

$$\operatorname{Ham}(X,\Pi) = \frac{1}{2} \int d\sigma \left(\partial_{\sigma} X \quad \Pi \right) \underbrace{\begin{pmatrix} G - BG^{-1}B & BG^{-1} \\ -G^{-1}B & G^{-1} \end{pmatrix}}_{\text{generalized metric } \mathcal{H}} \begin{pmatrix} \partial_{\sigma} X \\ \Pi \end{pmatrix}$$

[Tseytlin, 1990, Tseytlin, 1991]

Dynamics in the first order formulation

- ▶ time evolution for observable $\frac{\mathrm{d}}{\mathrm{d}\tau}f(X,\Pi) = \{f, \mathrm{Ham}\}$
- we need Poisson brackets

$$\begin{aligned} &\{X^{i}(\sigma), X^{j}(\sigma')\} = 0 \\ &\{X^{i}(\sigma), \Pi_{j}(\sigma')\} = \delta^{i}_{j}\delta(\sigma - \sigma') \\ &\{\Pi_{i}(\sigma), \Pi_{j}(\sigma')\} = 0 \end{aligned}$$

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When is it possible to

- 1. make the Hamiltonian quadratic
- 2. while keeping the "simple" Poisson brackets?

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$$\{J_I(\sigma), J_J(\sigma')\} = \eta_{IJ}\delta'(\sigma - \sigma')$$

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2. use $E_A^I(X)$ to transform

$$J_A' = E_A{}^I J_I$$
, $\eta_{AB} = E_A{}^I \eta_{IJ} E_B{}^J$, $\mathcal{H}_{AB} = E_A{}^I \mathcal{H}_{IJ} E_B{}^J$

then we get the brackets

$$\{J_A(\sigma),J_B(\sigma')\}={F_{AB}}^CJ_C\delta(\sigma-\sigma')+\eta_{AB}\delta'(\sigma-\sigma')$$
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the generalized Lie derivative

$$\mathcal{L}_{\left(\mathbf{X} \quad \phi\right)}\left(\mathbf{y} \quad \xi\right) = \begin{pmatrix} [\mathbf{X}, \mathbf{y}]_{\mathrm{Lie}} & L_{\mathbf{X}}\xi - L_{\mathbf{y}}\phi + \iota_{\mathbf{y}}\mathrm{d}\phi \end{pmatrix}$$

Motivation 00 Consistent truncations

Poisson-Lie T-duality

What means simple?

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- ▶ use Lie group element $g \in D$ generated by \mathfrak{d} to write

$$J_{A}=\langle T_{A},g^{-1}\partial_{\sigma}g\rangle$$

$$\operatorname{Ham} = \frac{1}{2} \int d\sigma \langle g^{-1} \partial_{\sigma} g, \mathcal{E} g^{-1} \partial_{\sigma} g \rangle \quad \mathcal{H}_{AB} = \langle T_A, \mathcal{E} T_B \rangle$$

► coined as *E*-model [Klimcik and Severa, 1996,Klimcik and Severa, 1996,Klimcik, 2015]

Poisson-Lie T-duality [Klimcik and Severa, 1995,Klimcik and Severa, 1996]

 \triangleright \mathcal{E} -model has target space D, dim D=2d

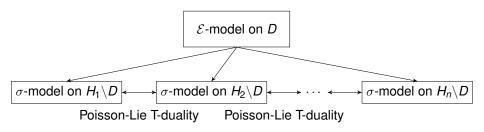
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- → integrate out d fields on maximally isotropic subgroup H
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- → integrate out d fields on maximally isotropic subgroup H
- ▶ physical target space $M=H\setminus D$
- in general different ways to choose H



Open questions

- complete the dictionary
- extension the Exceptional Field Theory
- include higher derivative corrections
- discuss branes
- what is the fade of supersymmetry
- applications to AdS/CFT

There is an intriguing web of relations between

Poisson-Lie symmetry, integrable deformations and (g)SUGRA.

It is quite likely the it will give rise to more interesting results in the future. Existing insights in one of them can lead to a better understanding of the others.