Surprisingly Complex Punctures from a Dynamical System

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in collaboration with

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THE UNIVERSITY of NORTH CAROLINA at CHAPEL HILL

Theories of class S [Gaiotto, 2012]

- $6D \; \mathcal{N} = (2,0) \; \text{SCFT}$
 - ▶ IIB on $\mathbb{R}^{5,1} \times \mathbb{C}^2 / \Gamma$, $\Gamma \subset SU(2) \rightarrow ADE$ -classification [Witten, 1995]
 - ► N M5-branes in flat space (A_N) [Strominger, 1996]

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 $4D\; \mathcal{N}=2\; SCFT$



Class *S*_Γ 00000 Dynamical system

N > 1 00

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 $4D \; \mathcal{N} = 2 \; \text{SCFT}$

- gauge group G
- flavor symmetry from punctures on Σ

Class S
0000

Class *S*_Γ 00000 Dynamical system

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S-duality of 4D N=2 SU(2) with $N_f = 4$ flavors [Seiberg and Witten, 1994]

▶ flavor enhances to SO(8) \supset SO(2)_a×SO(2)_b× SO(2)_c×SO(2)_d

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- weak coupling limit $\tau \to i\infty$
- S-duality is SL(2, ℤ) action on complex structure moduli space



Constrains on punctures

• compactify 6D $\mathcal{N} = (2,0)$ on S^1



▶ 5D *N*=2 gauge theory with matter in bifundamental of *G*

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$$\Sigma(t) = rac{\Sigma}{t}$$
 $Q(t) = rac{Q}{t}$ $ilde{Q}(t) = 0$

(in terms of \mathcal{N} =1 4D superfields)

results in Nahm pole equations [Nahm, 1980]

$$[\Sigma, Q] = Q$$
 $[Q, Q^{\dagger}] = \Sigma$

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► Σ , Q, Q^{\dagger} are representations of $\mathfrak{su}(2)$

Class S ○○●○ Class *S*_Γ 00000 Dynamical system

N > 1 00

• *Q* is a nilpotent $|\Gamma| \times |\Gamma|$ matrix \rightarrow Jordan normal form

e.g.
$$Q = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$
 $\Sigma = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$

a compact representation is the Young diagram

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e.g.
$$Q = \begin{pmatrix} 0 & 1/\sqrt{2} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$
 $\Sigma = \begin{pmatrix} 1/2 & 0 & 0 \\ 0 & -1/2 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

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Class S

0000

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Summary

Dynamical system

Class S

0000

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: Generalization to $\mathcal{N}=1$?

▶ 6D *N* = (1,0) SCFT

► compactification Σ with punctures \rightarrow 4D N=1 SCFTs ^{[Razamat, Vafa, and}

Zafrir, 2016]



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Challenges

▶ much more 6D $\mathcal{N} = (1,0)$ than $\mathcal{N} = (2,0)$ SCFTs ^{[Heckman, Morrison,}

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- less constrained by SUSY
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- 4.00



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- use "simple" 6D N=(1,0) SCFT
 N M5-branes probing ADE-singularity C²/Γ
- try to classify all punctures [Heckman, Jefferson,

Rudelius, and Vafa, 2017]

harder than you might think

Dynamical system

N > 1 00

Theories of Class S_{Γ} ... [Heckman, Jefferson, Rudelius, and Vafa, 2017]

- stack of N M5-branes probing ADE-singularity C²/Γ
- ▶ compactification on $S^1 \rightarrow 5D$ quiver gauge theory

Theories of Class S_{[...} [Heckman, Jefferson, Rudelius, and Vafa, 2017]

- stack of N M5-branes probing ADE-singularity C²/Γ
- compactification on $S^1
 ightarrow 5D$ quiver gauge theory
- organized according to extended Dynkin diagrams



... and their punctures

• again, maximally SUSY punctures \rightarrow 1/2 BPS equations for

$$\Sigma(t) = rac{\Sigma}{t}$$
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(in terms of $\mathcal{N}=1$ 4D superfields in covering space)

results in generalized Nahm pole equations [Heckman, Jefferson, Rudelius, and Vafa, 2

$$\begin{split} [\Sigma, Q] &= Q & [Q, \tilde{Q}] = 0 \\ [\Sigma, \tilde{Q}] &= \tilde{Q} & [Q, Q^{\dagger}] + [\tilde{Q}, \tilde{Q}^{\dagger}] = \Sigma \end{split}$$

plus invariance under **Γ**-action with

doublet
$$\begin{pmatrix} Q \\ \tilde{Q} \end{pmatrix}$$
 and singlet Σ

Class S

Dynamical system

N > 1 00

A closer look at \widehat{A}_k quivers

• choose
$$\Gamma \ni \gamma = \text{diag}(\mathbf{1}_N, \omega \mathbf{1}_N, \omega^2 \mathbf{1}_N, \dots, \omega^k \mathbf{1}_N)$$

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$$\gamma \mathbf{Q} \gamma^{\dagger} = \mathbf{Q} \qquad \gamma \tilde{\mathbf{Q}} \gamma^{\dagger} = \tilde{\mathbf{Q}} \qquad \gamma \Sigma \gamma^{\dagger} = \mathbf{0}$$

$$\Sigma = \begin{pmatrix} p(1) & & \\ & \ddots & \\ & & p(k) \end{pmatrix} \qquad \mathbf{Q} = \begin{pmatrix} q(1) & & \\ & \ddots & \\ & & q(k-1) \end{pmatrix} \qquad \tilde{\mathbf{Q}} = \begin{pmatrix} \tilde{q}(1) & & & \\ & \ddots & & \\ & & \tilde{q}(k-1) \end{pmatrix}$$



Finding punctures reduces to a "simple" problem in algebra

Problem

- 1. take $N|\Gamma| \times N|\Gamma|$ matrices Q, \tilde{Q} and Σ
- 2. restrict them to fit the ADE-type of Γ
- 3. find all fulfilling the generalized Nahm pole equations
- more complicated than we initially thought
- even for the simplest case N=1 \hat{A}_k quivers



▶ rewrite gen. Nahm pole eq. in terms of q(i), $\tilde{q}(i)$ and p(i)

$$[Q, \tilde{Q}] = 0 \rightarrow q(i+1)\tilde{q}(i+1) = q(i)\tilde{q}(i)$$
$$[Q, Q^{\dagger}] + [\tilde{Q}, \tilde{Q}^{\dagger}] = \Sigma \rightarrow x(i) - x(i-1) = p(i)$$
$$[\Sigma, Q] = Q \rightarrow q(i)(p(i) - p(i+1)) = q(i)$$
$$[\Sigma, \tilde{Q}] = \tilde{Q} \rightarrow -\tilde{q}(i)(p(i) - p(i+1)) = \tilde{q}(i)$$
with $x(i) = q(i)q(i)^* - \tilde{q}(i)\tilde{q}(i)^*$

Class *S*Γ 00000 Dynamical system

 $\substack{N>1\0}$

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with $x(i) = q(i)q(i)^* - \tilde{q}(i)\tilde{q}(i)^*$
Q is nilpotent, thus $Q^k = 1_k \prod_{i=1}^k q(i) = 0 \rightarrow q(i)\tilde{q}(i) = 0$

knowing x(i) is sufficient to get q(i) and q̃(i)

Class S

► rewrite gen. Nahm pole eq. in terms of q(i), q̃(i) and p(i) with x(i) = q(i)q(i)* - q̃(i)q̃(i)*

discrete dynamical system

$$f: \begin{pmatrix} p \\ x \end{pmatrix} (i+1) = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} p \\ x \end{pmatrix} (i) - \operatorname{sgn} x(i)$$

Class *S*Γ 00000 Dynamical system

 $\substack{N>1\0}{00}$

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- choose x(1), p(1) and all other x(i), p(i) are fixed¹
- 1 In general p(i + 1) is unconstrained if x(i) = 0. We choose p(i + 1)=p(i) to formally extend the dynamical system beyond this point.

Dynamical system

- punctures = periodic orbits of length $k = |\Gamma|$
- strongly depends on the initial condition, e.g.

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Class S

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Dynamical system

N > 1 00

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Class *S*Γ 00000 Dynamical system

N > 1

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Class S

▶ if x(k)=0 then p(1)=x(1)=I, iterate line instead of point



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Class S

Class *S*_Γ

Dynamical system

N > 1

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Class S

Class S_Γ

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Class S

Class *S*_Γ 00000 Dynamical system

N > 1 00

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A tree of solutions

• periodic orbits of type () x(k) = 0 organized in tree structure



Class S

Class *S*_Γ 00000 Dynamical system

N > 1

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Class S

Class *S*Γ 00000 Dynamical system

N > 1

Results, quantitative

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 short orbits () and olong orbits ()

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 short orbits and olong orbits
- ▶ for solution of length *k*

$$l \in \frac{1}{2k} \Big\{ -k(k-1), -k(k-1)+4, \ldots, k(k-1) \Big\}$$

• not all elements in this set are realized, # solutions $< k^2$

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- not all elements in this set are realized, # solutions $< k^2$
- all relevant information encoded in sgn x(i)
- for all periodic orbits

$$\sum_{i=1}^k \operatorname{sgn} x(i) = 0$$

Dynamical system

the tree of solutions is surprisingly complex



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- any pattern? e.g. self similar like Barnsley's fern?



Dynamical system

N > 1 00

- the tree of solutions is surprisingly complex
- any pattern? e.g. self similar like Barnsley's fern?
- even # of solutions has interesting structure



Periodic orbits with $x(k) \neq 0$

- apply "divide and conquer" algorithm to
 each *p*(1) ∈ set of allowed *p* and *x*(1) = *l*
- slow but guaranteed to find all solutions

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► faster: take
$$\bigcirc x(k_1)=0$$
 and shift it slightly $p(1) = l_1$ and $x(1) = l_1 + \Delta$

• sufficiently small Δ , only sgn $x(k_1)$ changes

$$p(k_1) = \underbrace{g(l_1) - \operatorname{sgn} \Delta}_{l_2}$$
 and $x(k_1) = \underbrace{p(k_1) + \Delta}_{l_2 + \Delta}$

Class *S*Γ 00000 Dynamical system

N > 1 00

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iterate

$$l_{i+1} = g(l_i) - \operatorname{sgn} \Delta$$

until $l_n = l_1$

Dynamical system

N > 1

consider higher poles for 1/2 BPS equations

$$\Sigma(t) = \sum_{n=1}^{\infty} \frac{\Sigma_n}{t^{-n}} \qquad \qquad Q(t) = \sum_{n=1}^{\infty} \frac{Q_n}{t^{-n}} \qquad \qquad \tilde{Q}(t) = \sum_{n=1}^{\infty} \frac{\tilde{Q}_n}{t^{-n}}$$

results in the puncture equations [Heckman, Jefferson, Rudelius, and Vafa, 2017]

$$\sum_{k+l=m} [\Sigma_k, Q_l] = (m-1)Q_{m-1} \qquad \sum_{k+l=m} [Q_k, \tilde{Q}_l] = 0$$
$$\sum_{k+l=m} [\Sigma_k, \tilde{Q}_l] = (m-1)\tilde{Q}_{m-1} \qquad \sum_{k+l=m} [Q_k, Q_l^{\dagger}] + [\tilde{Q}_k, \tilde{Q}_l^{\dagger}] = (m-1)\Sigma_{m-1}$$

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▶ linear in unknown quantities, e.g.
 m=3: [*Q*₁, *Q*₂] + [*Q*₂, *Q*₁] = 0

Class S

Class *S*_Γ 00000 Dynamical system

N > 1 00

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Class S

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- ▶ linear in unknown quantities, e.g.
 m=4: [Q₁, Q₃] + [Q₂, Q₂] + [Q₃, Q₁] = 0
- ▶ permits solution order by order with $Q_1 = Q$, $\tilde{Q}_1 = \tilde{Q}$ and $\Sigma_1 = \Sigma$

Class S

Class *S*Γ 00000 Dynamical system

and another dynamical system

► for
$$\vec{v}_m(i) = (q_m \quad \tilde{q}_m \quad p_m)^T$$

$$f_m: \vec{v}_m(i+1) = M_m(i)\vec{v}_m(i) + \vec{n}_m(i)$$

$$\begin{pmatrix} -\alpha_m(i) + \beta_m(i) & 0 & \delta_m(i) \\ 0 & \beta_m(i) & 0 \\ -\gamma_m & 0 & 1 \\ 0 & \beta_m(i) & 0 \\ \alpha_m(i) - \beta_m(i) & 0 & -\delta_m(i) \\ 0 & \alpha_m(i) - \beta_m(i) & 0 & -\delta_m(i) \\ -\gamma_m(i) & 0 & 1 \end{pmatrix} \text{ for } x(i) > 0 \text{ and } x(i+1) < 0$$

$$M_m(i) = \begin{cases} (-\alpha_m(i) + \beta_m(i) & 0 & \delta_m(i) \\ 0 & \beta_m(i) & 0 \\ -\gamma_m(i) & 0 & -\delta_m(i) \\ -\gamma_m(i) & 0 & 1 \\ 0 & 0 & 0 \end{cases} \text{ for } x(i) > 0 \text{ and } x(i+1) < 0$$

$$\begin{split} i) &= \begin{cases} \begin{pmatrix} & -\gamma_m(i) & 0 & 1 \\ 0 & \alpha_m(i) - \beta_m(i) & \delta_m(i) \\ \beta_m(i) & 0 & 0 \\ 0 & \gamma_m(i) & 1 \\ \begin{pmatrix} \beta_m(i) & 0 & 0 \\ 0 & -\alpha_m(i) + \beta_m(i) & -\delta_m(i) \\ 0 & \gamma_m(i) & 1 \\ \end{cases} \quad \text{for } x(i) < 0 \text{ and } x(i+1) < 0 \\ \text{for } x(i) < 0 \text{ and } x(i+1) < 0 \\ i) &= \gamma_m(i)\delta_m(i), \quad \beta_m(i) = \sqrt{\left|\frac{x(i)}{x(i+1)}\right|}, \quad \gamma_m(i) = \frac{m-2}{\sqrt{|x(i)|}}, \quad \delta_m(i) = \frac{m-1}{2\sqrt{|x(i+1)|}} \\ \text{for } Class \ S_{\Gamma} & \text{Dynamical system} \end{cases}$$

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N > 1 00 Summary

Class S

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and another dynamical system

• for
$$\vec{v}_m(i) = (q_m \quad \tilde{q}_m \quad p_m)^T$$

$$f_m: \vec{v}_m(i+1) = M_m(i)\vec{v}_m(i) + \vec{n}_m(i)$$

find periodic orbit of length k

$$f_m^k = \vec{v}_m(k+1) = \mathbf{M}_m \vec{v}_m(1) + \vec{\mathbf{n}}_m = \vec{v}_m(1)$$

and another dynamical system

- ► for $\vec{v}_m(i) = (q_m \quad \tilde{q}_m \quad p_m)^T$ $f_m: \vec{v}_m(i+1) = M_m(i)\vec{v}_m(i) + \vec{n}_m(i)$ (x) no orbit (n) *n*-dim. family
- find periodic orbit of length k



- \blacktriangleright remember: punctures for $\mathcal{N}=2 \rightarrow$ Young diagrams
- ho $\mathcal{N}=1$ class $S_{\Gamma},$ $N\!=\!1,$ $\Gamma=\mathbb{Z}_k,$ $ilde{Q}=0$ [Heckman, Jefferson, Rudelius, and Vafa, 2017]



decorated with **Γ**-charge

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decorated with **Γ**-charge

• many new options away from $\mathfrak{su}(2)$ branch, e.g. $l_1 = 1/3$

- \blacktriangleright remember: punctures for $\mathcal{N}=2 \rightarrow$ Young diagrams
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decorated with **Γ**-charge

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- many new options away from $\mathfrak{su}(2)$ branch, e.g. $l_1 = 1/3$
- some of them can be shifted to $\begin{pmatrix} \\ \end{pmatrix}$ with extra d.f. x(1)
- x(1) can be tuned to gives add d.f. for h.o. punctures

Example

$$p(1) = \frac{3}{2}$$
 $x(1) = 0.8805582419579654$

Class S 0000 **Class S_Γ** 00000 Dynamical system

N > 1 00

$N > 1 \ \widehat{A}_k$ quivers are challenging

remember N=1: for each "time step" solve

 $x(i) = q(i)q(i)^* - \tilde{q}(i)\tilde{q}(i)^*$ and $0 = q(i)\tilde{q}(i)$

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- ▶ use *N* decoupled copy of the *N*=1 system
- embedding into u(k) with irreps > fundamental

Embedding of \bigcirc into $\mathfrak{su}(k)$

- Q, \tilde{Q}, Σ are elements of $\mathfrak{su}(k)$ in the fundamental irrep
- to use other irreps
 - 1. tensor them *n* times
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$k \setminus N$	1	2	3	4	5
3	3	6			15
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6	6				
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• example **10** of $\mathfrak{su}(5)$ with I = 2/5

Class S

Class *S*_Г 00000

Dynamical system

Summary

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Even for the simplest class S_{Γ} theories, the punctures show an amazingly rice structure compared to the $\mathcal{N} = 2$ case.

still lots of questions

- quantitative measure for complexity
- connection to spin chain
- statistical properties of solutions
- are the characteristic quantities for a puncture
- ► can we do more for N > 1, e.g. large N limit AdS/CFT