

# Double Field Theory on Group Manifolds

Falk Haßler

in collaboration with

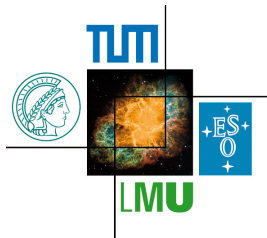
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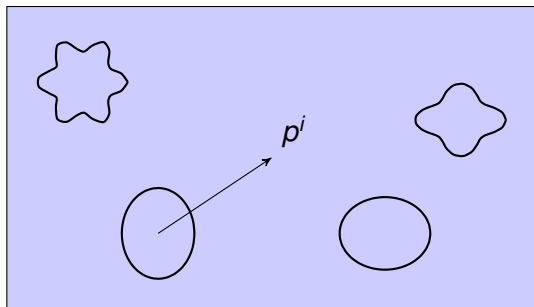
Max-Planck-Institut für Physik  
(Werner-Heisenberg-Institut)



## SUGRA

- ▶ closed strings in  $D$ -dim. flat space with momentum  $p^i$
- ▶ truncate all massive excitations
- ▶ match scattering amplitudes of strings with EFT

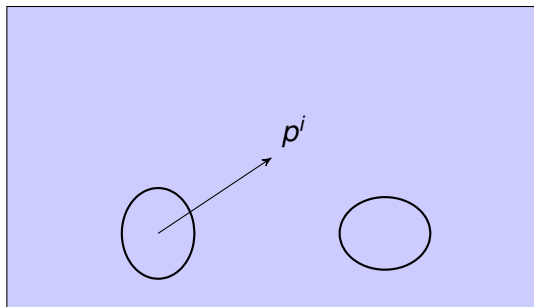
$$S_{\text{NS}} = \int d^D x \sqrt{g} e^{-2\phi} \left( \mathcal{R} + 4\partial_i \phi \partial^i \phi - \frac{1}{12} H_{ijk} H^{ijk} \right)$$



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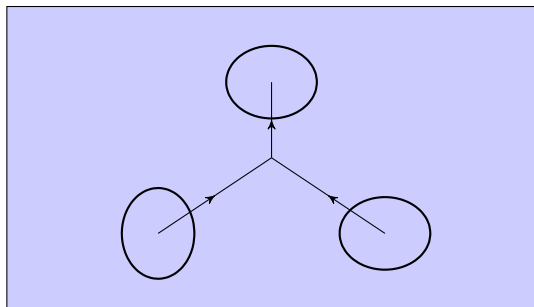
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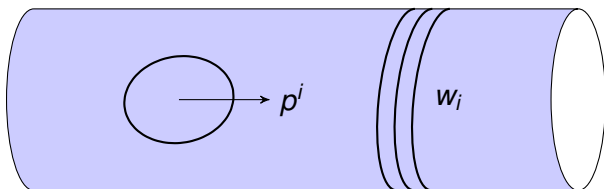
## DFT (Double Field Theory) [Siegel, 1993, Hull and Zwiebach, 2009, Hohm, Hull, and Zwiebach, 2010]

- ▶ closed strings on a flat torus with momentum  $p^i$  and winding  $w_i$
- ▶ combine conjugated variables  $x_i$  and  $\tilde{x}^i$  into  $X^M = (\tilde{x}_i \ x^i)$
- ▶ repeat steps from SUGRA derivation

$$S_{\text{DFT}} = \int d^{2D} X e^{-2d} \mathcal{R}(\mathcal{H}_{MN}, d)$$

- ▶ fields are constrained by strong constraint

$$\partial_M \partial^M \cdot = 0$$



## Key questions

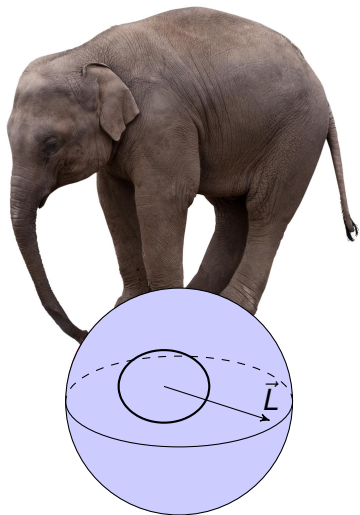
- ▶ Is DFT more general than SUGRA?
- ▶ Is DFT really background independent?
- ▶ Can we relax the strong constraint?

$S^3$ , my elephant in the room



- ▶ switch on  $H$ -flux, solve eom

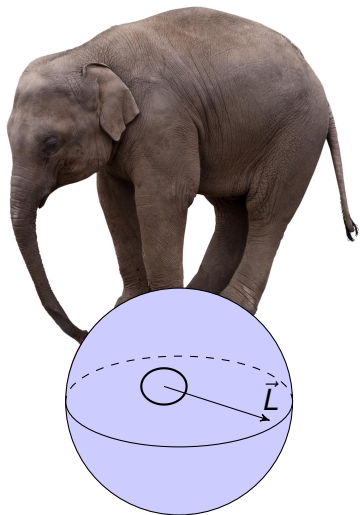
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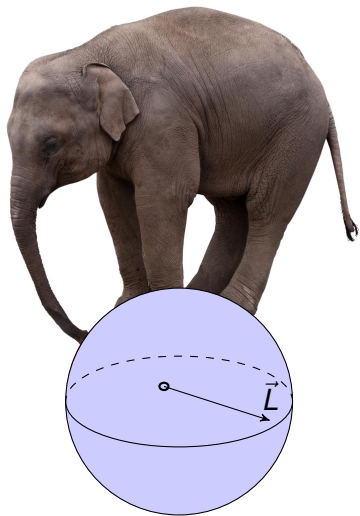


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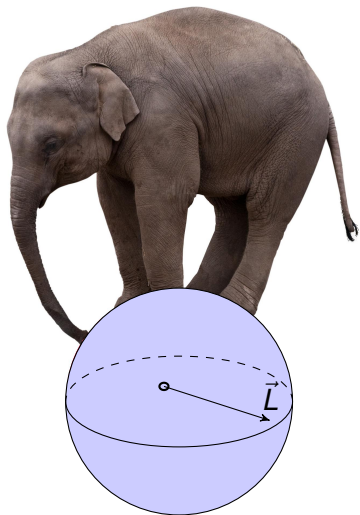
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¿winding?

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$$\text{DFT}_{\text{WZW}} \supset \text{DFT}$$

**NEW!**

strong constraint

**NEW!**

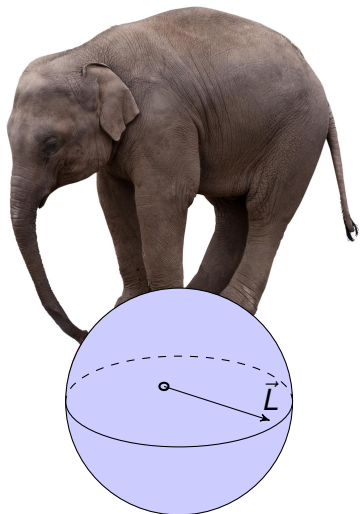
action

**NEW!**

symmetries

¿winding?

# $S^3$ , my elephant in the room



- ▶ switch on  $H$ -flux, solve eom
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**NEW!**

strong constraint

**NEW!**

action

**NEW!**

symmetries

**FREE**

twist gen. Scherk-Schwarz

**FREE**

genuinely non-geometric backgr.

¿winding?

# Outline

1. Deriving  $DFT_{WZW}$  from CSFT 1410.6374
2. Generalized metric formulation 1502.02428
3. Flux formulation 1507.?????
4. Summary and outlook

## DFT<sub>WZW</sub> = DFT on group manifolds



Use group manifold instead of a torus to derive DFT!

+ includes  $\begin{cases} T^D = U(1)^D \\ S^3 = SU(2) \end{cases}$

+ CFT exactly solvable

+ flux backgrounds with const. fluxes

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Double Field Theory =

- ▶ treat left and right mover independently
- ▶  $2D$  independent coordinates

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$$x^i = \frac{1}{\sqrt{2}}(x_L^i + x_R^i)$$
$$\tilde{x}_i = \frac{1}{\sqrt{2}}(x_{Li} - x_{Ri})$$

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## Questions about DFT<sub>WZW</sub>

- ▶ What are the covariant objects?
- ▶ How is it connected to DFT?
- ▶ Does it make non-abelian duality manifest?

} not trivial

## WZW model & Kač-Moody algebra [Witten, 1983, Walton, 1999]

- ▶  $g \in G$ , a compact simply connected Lie group

$$S_{\text{WZW}} = \frac{1}{2\pi\alpha'} \int_M d^2z \mathcal{K}(g^{-1}\partial g, g^{-1}\bar{\partial}g) + S_{\text{WZ}}(g)$$

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- ▶ metric and 3-form flux in flat indices

$$\eta_{ab} := \mathcal{K}(t_a, t_b) \quad \text{and} \quad F_{abc} := \mathcal{K}([t_a, t_b], t_c)$$

- ▶  $D$  chiral and  $D$  anti-chiral Noether currents (=2D indep. currents)

$$j_a(z) = \frac{2}{\alpha'} \mathcal{K}(\partial g g^{-1}, t_a) \quad \text{and} \quad \bar{j}_{\bar{a}}(\bar{z}) = -\frac{2}{\alpha'} \mathcal{K}(g^{-1}\bar{\partial}g, t_{\bar{a}})$$

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- ▶ radial quantization

$$j_a(z)j_b(w) = -\frac{\alpha'}{2} \frac{1}{(z-w)^2} \eta_{ab} + \frac{1}{z-w} F_{ab}{}^c j_c(z) + \dots$$

## Action

- ▶ tree level action in CSFT [Zwiebach, 1993]

$$(2\kappa^2)\mathcal{S} = \frac{2}{\alpha'} \left( \langle \Psi | c_0^- Q | \Psi \rangle + \frac{1}{3} \{ \Psi, \Psi, \Psi \}_0 + \dots \right)$$

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- ▶ string field for massless excitations [Hull and Zwiebach, 2009]

$$|\Psi\rangle = \sum_R \left[ \frac{\alpha'}{4} \epsilon^{a\bar{b}}(R) j_{a-1} j_{\bar{b}-1} c_1 \bar{c}_1 + e(R) c_1 c_{-1} + \bar{e}(R) \bar{c}_1 \bar{c}_{-1} + \frac{\alpha'}{2} (f^a(R) c_0^+ c_1 j_{a-1} + f^{\bar{b}}(R) c_0^+ \bar{c}_1 j_{\bar{b}-1}) \right] |\phi_R\rangle$$

- ▶  $R$  is highest weight of  $\mathfrak{g} \times \mathfrak{g}$  representation

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- ▶  $R$  is highest weight of  $\mathfrak{g} \times \mathfrak{g}$  representation
- ▶ BRST operator ( $L_m$  from Sugawara construction)

$$Q = \sum_m \left( : c_{-m} L_m : + \frac{1}{2} : c_{-m} L_m^{gh} : \right) + \text{anti-chiral}$$

## Geometric representation of primary fields ( $k \rightarrow \infty$ )

► flat derivative

$$D_a = e_a^i \partial_i \quad \text{with} \quad e_a^i = \mathcal{K}(g^{-1} \partial^j g, t_a)$$

operator algebra	geometry ( $j_{a0} \rightarrow D_a$ )
$L_0  \phi_R\rangle = j_{a0} j_0^a  \phi_R\rangle = h_R  \phi_R\rangle$	$D_a D^a Y_R(x^i) = h_R Y_R(x^i)$
$[j_{a0}, j_{b0}] = F_{ab}^c j_{c0}$	$[D_a, D_b] = F_{ab}^c D_c$
$\sum_R e(R)  \phi_R\rangle$	$\sum_R e(R) Y_R(x^i) := e(x^i)$



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$$E_A^I = \begin{pmatrix} e_a^i & 0 \\ 0 & e_{\bar{a}}^{\bar{i}} \end{pmatrix}$$

$$S_{AB} = 2 \begin{pmatrix} \eta_{ab} & 0 \\ 0 & \eta_{\bar{a}\bar{b}} \end{pmatrix}$$

$$\eta_{AB} = 2 \begin{pmatrix} \eta_{ab} & 0 \\ 0 & -\eta_{\bar{a}\bar{b}} \end{pmatrix}$$

## Weak constraint (level matching), later strong constraint

- ▶ level matched string field  $(L_0 - \bar{L}_0)|\Psi\rangle = 0$  requires

$$(D_a D^a - D_{\bar{a}} D^{\bar{a}}) \cdot = 0 \quad \text{with} \quad \cdot \in \{\epsilon^{a\bar{b}}, e, \bar{e}, f^a, f^{\bar{b}}\}$$

- ▶ rewritten in terms of  $\eta^{AB}$  and  $D_A = (D_a \quad D_{\bar{a}})$

$$\eta^{AB} D_A D_B \cdot = D_A D^A \cdot = 0$$

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- ▶ change to curved indices using  $E_A^M$

$$(\partial_M \partial^M - 2\partial_M d \partial^M) \cdot = 0 \quad \text{with} \quad d = \phi - \frac{1}{2} \log \sqrt{g}$$


- ▶  **NEW!** term which is absent in DFT  $\rightarrow$  adsorb in cov. derivative

$$\boxed{\nabla_M \partial^M \cdot = 0} \quad \text{with} \quad \nabla_M V^N = \partial_M V^N + \Gamma_{MK}^N V^K, \quad \Gamma_{MK}^M = -2\partial_K d$$

## Results (leading order $k^{-1}$ )

- ▶ calculate quadratic and cubic string functions
- ▶ integrate out auxiliary fields  $f^a$  and  $f^{\bar{b}}$
- ▶ perform field redefinition

$$(2\kappa^2)S = \int d^{2D}X \sqrt{H} \left[ \frac{1}{4} \epsilon_{a\bar{b}} \square \epsilon^{a\bar{b}} + \dots \right. \\ \left. - \frac{1}{4} \epsilon_{a\bar{b}} (F^{ac}{}_d \bar{D}^{\bar{e}} \epsilon^{d\bar{b}} \epsilon_{c\bar{e}} + F^{\bar{b}\bar{c}}{}_{\bar{d}} D^e \epsilon^{a\bar{d}} \epsilon_{e\bar{c}}) \right. \\ \left. - \frac{1}{12} F^{ace} F^{\bar{b}\bar{d}\bar{f}} \epsilon_{a\bar{b}} \epsilon_{c\bar{d}} \epsilon_{e\bar{f}} + \dots \right]$$

- ▶  **NEW** terms e.g. potential
- ▶ vanish in abelian limit  $F_{abc} \rightarrow 0$  and  $F_{\bar{a}\bar{b}\bar{c}} \rightarrow 0$

## Gauge transformations

- ▶ tree level gauge transformation in CSFT [Zwiebach, 1993]

$$\delta_{\Lambda}|\Psi\rangle = Q|\Lambda\rangle + [\Lambda, \Psi]_0 + \dots$$

- ▶ string field for gauge parameter [Hull and Zwiebach, 2009]

$$|\Lambda\rangle = \sum_R \left[ \frac{1}{2} \lambda^a(R) j_{a-1} c_1 - \frac{1}{2} \lambda^{\bar{b}}(R) j_{\bar{b}-1} \bar{c}_1 + \mu(R) c_0^+ \right] |\phi_R\rangle$$

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- ▶ after field redefinition and  $\mu$  gauge fixing

$$\delta_\lambda \epsilon_{a\bar{b}} = D_{\bar{b}} \lambda_a + \frac{1}{2} \left[ D_a \lambda^c \epsilon_{c\bar{b}} - D^c \lambda_a \epsilon_{c\bar{b}} + \lambda_c D^c \epsilon_{a\bar{b}} + F_{ac}{}^d \lambda^c \epsilon_{d\bar{b}} \right]$$

$$D_a \lambda_{\bar{b}} + \frac{1}{2} \left[ D_{\bar{b}} \lambda^{\bar{c}} \epsilon_{a\bar{c}} - D^{\bar{c}} \lambda_{\bar{b}} \epsilon_{a\bar{c}} + \lambda_{\bar{c}} D^{\bar{c}} \epsilon_{a\bar{b}} + F_{\bar{b}\bar{c}}{}^{\bar{d}} \lambda^{\bar{c}} \epsilon_{a\bar{d}} \right]$$

$$\delta_\lambda d = -\frac{1}{4} D_a \lambda^a + \frac{1}{2} \lambda_a D^a d - \frac{1}{4} D_{\bar{a}} \lambda^{\bar{a}} + \frac{1}{2} \lambda_{\bar{a}} D^{\bar{a}} d$$

## Doubled objects

promising results, but bulky



Rewrite action/gauge trafo in terms of doubled object

- + simplifies expressions considerably
- + extrapolation from cubic to all order in fields

## Doubled objects

object	doubled version
$\eta_{ab}, \eta_{\bar{a}\bar{b}}$	$\eta_{AB} = 2 \begin{pmatrix} \eta_{ab} & 0 \\ 0 & -\eta_{\bar{a}\bar{b}} \end{pmatrix} \quad S_{AB} = 2 \begin{pmatrix} \eta_{ab} & 0 \\ 0 & \eta_{\bar{a}\bar{b}} \end{pmatrix}$
$e_a^i, e_{\bar{a}}^{\bar{i}}$	$E_A^I = \begin{pmatrix} e_a^i & 0 \\ 0 & e_{\bar{a}}^{\bar{i}} \end{pmatrix}$
$D_a, D_{\bar{a}}$	$D_A = (D_a \quad D_{\bar{a}}) = E_A^I \partial_I \quad \text{with} \quad \partial_I = (\partial_i \quad \partial_{\bar{i}})$



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$D_a, D_{\bar{a}}$	$D_A = (D_a \ D_{\bar{a}}) = E_A^I \partial_I \quad \text{with} \quad \partial_I = (\partial_i \ \partial_{\bar{i}})$
$\xi^i, \xi^{\bar{i}}$	$\xi^I = (\xi^i \ \xi^{\bar{i}})$
$F_{ab}{}^c, F_{\bar{a}\bar{b}}{}^{\bar{c}}$	$F_{AB}{}^C = \begin{cases} F_{ab}{}^c \\ F_{\bar{a}\bar{b}}{}^{\bar{c}} \\ 0 \end{cases} \quad \text{otherw.} \quad [D_A, D_B] = F_{AB}{}^C D_C$

## Gauge transformations

- ▶ “doubled” version of fluctuations  $\epsilon^{a\bar{b}}$

$$\epsilon^{AB} = \begin{pmatrix} 0 & -\epsilon^{a\bar{b}} \\ -\epsilon^{\bar{a}b} & 0 \end{pmatrix} \quad \text{with} \quad \epsilon^{a\bar{b}} = (\epsilon^T)^{\bar{b}a}$$

- ▶ generate generalized metric [Hohm, Hull, and Zwiebach, 2010]

$$\mathcal{H}^{AB} = S^{AB} + \epsilon^{AB} + \frac{1}{2}\epsilon^{AC} S_{CD}\epsilon^{DB} + \dots = \exp(\epsilon^{AB})$$

with the defining property  $\mathcal{H}^{AC}\eta_{CD}\mathcal{H}^{DB} = \eta^{AB}$

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- ▶ generalized Lie derivative [Hull and Zwiebach, 2009, Grana and Marques, 2012]

$$\begin{aligned} \mathcal{L}_\lambda \mathcal{H}^{AB} = & \lambda^C D_C \mathcal{H}^{AB} + (D^A \lambda_C - D_C \lambda^A) \epsilon^{CB} + \\ & (D^B \lambda_C - D_C \lambda^B) \mathcal{H}^{AC} + F^A_{CD} \lambda^C \mathcal{H}^{DB} + F^B_{CD} \lambda^C \mathcal{H}^{AD} \end{aligned}$$

- ▶ setting  $\delta_\lambda S^{AB} := 0$  and using

$$\delta_\lambda \epsilon^{AB} = \mathcal{L}_\lambda S^{AB} + \mathcal{L}_\lambda \epsilon^{AB} + \mathcal{L}_\lambda S^{(A} S^{B)}_C \epsilon^{CD}.$$

results in  $\boxed{\delta_\lambda \mathcal{H}^{AB} = \mathcal{L}_\lambda \mathcal{H}^{AB} + \mathcal{O}(\epsilon^2)}$

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- ▶ similar for the generalized dilaton  $d$
- ▶ introduce covariant derivative

$$\nabla_A V^B = D_A V^B + \frac{1}{3} F^B_{AC} V^C$$

- ▶  **NEW!** generalized Lie derivative, e.g. for vector

$$\mathcal{L}_\lambda V^A = \lambda^B \nabla_B V^A + (\nabla^A \lambda_B - \nabla_B \lambda^A) V^B \quad \text{instead of}$$

$$\mathcal{L}_\lambda V^I = \lambda^J \partial_J V^I + (\partial^I \lambda_J - \partial_J \lambda^I) V^J \quad \text{in traditional DFT}$$

## Gauge algebra

- ▶ CSFT to cubic order fulfills

$$\delta_{\Lambda_1} \delta_{\Lambda_2} - \delta_{\Lambda_2} \delta_{\Lambda_1} = \delta_{\Lambda_{12}} \quad \text{with} \quad \Lambda_{12} = [\Lambda_2, \Lambda_1]_0$$

- ▶ after field redefinition and  $\mu$  fixing  $\lambda_{12}^A = [\lambda_2, \lambda_1]_C^A$  with

$$[\lambda_1, \lambda_2]_C^A = \lambda_1^B \nabla_B \lambda_2^A - \frac{1}{2} \lambda_1^B \nabla^A \lambda_{2B} - (1 \leftrightarrow 2)$$

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$$\delta_{\Lambda_1} \delta_{\Lambda_2} - \delta_{\Lambda_2} \delta_{\Lambda_1} = \delta_{\Lambda_{12}} \quad \text{with} \quad \Lambda_{12} = [\Lambda_2, \Lambda_1]_0$$

- ▶ after field redefinition and  $\mu$  fixing  $\lambda_{12}^A = [\lambda_2, \lambda_1]_C^A$  with

$$[\lambda_1, \lambda_2]_C^A = \lambda_1^B \nabla_B \lambda_2^A - \frac{1}{2} \lambda_1^B \nabla^A \lambda_{2B} - (1 \leftrightarrow 2)$$

- ▶ algebra closes up to a trivial gauge transformation if

1. fluctuations and parameter fulfill **NEW!** strong constraint  $D_A D^A$ .
2. background fulfills Jacobi identity

$$F_{E[AB} F^E_{C]D} = 0$$

- ▶ no strong constraint required for background

- ▶ non-vanishing torsion and Riemann curvature

$$[\nabla_A, \nabla_B]V_C = R_{ABC}{}^D V_D - T^D{}_{AB}\nabla_D V_C \quad \text{with}$$

$$T^A{}_{BC} = -\frac{1}{3}F^A{}_{BC} \quad \text{and} \quad R_{ABC}{}^D = \frac{2}{9}F_{AB}{}^E F_{EC}{}^D$$



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- ▶ compatible with  $E_A{}^I$ ,  $\eta_{AB}$  and  $S_{AB}$

$$\nabla_C E_A{}^I = \nabla_C \eta_{AB} = \nabla_C S_{AB} = 0$$

- ▶ compatible with partial integration

$$\int d^{2D} X e^{-2d} U \nabla_M V^M = - \int d^{2D} X e^{-2d} \nabla_M U V^M$$

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- ▶ non-vanishing generalized torsion

## Action

$$X^I = (x^i \quad x^{\bar{i}})$$

$$S = \int d^{2D} X e^{-2d} \mathcal{R}(\mathcal{H}_{MN}, d)$$


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$$\begin{aligned} \mathcal{R} = & 4\mathcal{H}^{MN} \nabla_M \nabla_N d - \nabla_M \nabla_N \mathcal{H}^{MN} - 4\mathcal{H}^{MN} \nabla_M d \nabla_N d + 4\nabla_M \mathcal{H}^{MN} \nabla_N d \\ & + \frac{1}{8} \mathcal{H}^{MN} \nabla_M \mathcal{H}^{KL} \nabla_N \mathcal{H}_{KL} - \frac{1}{2} \mathcal{H}^{MN} \nabla_N \mathcal{H}^{KL} \nabla_L \mathcal{H}_{MK} + \frac{1}{6} F_{MKL} F_N{}^{KL} H^{MN} \end{aligned}$$

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- ▶ lower indices with  $\eta_{MN} = E^A{}_M E^B{}_N \eta_{AB} \neq \text{const.}$
- ▶  $H_{IJ} = E^A{}_M E^B{}_N S_{AB}$  background generalized metric

$$\nabla_M d = \partial_M \tilde{d}$$

$$\nabla_M \mathcal{H}^{KL} = \partial_M \mathcal{H}^{KL} + \Gamma_{MJ}{}^K \mathcal{H}^{JL} + \Gamma_{MJ}{}^L \mathcal{H}^{KJ}$$

## Symmetries

- ▶ generalized diffeomorphisms (only under strong constraint)

$$\delta_\xi \mathcal{H}^{MN} = \mathcal{L}_\xi \mathcal{H}^{MN}$$

$$\delta_\xi d = \mathcal{L}_\xi d = \xi^M \nabla_M d + \frac{1}{2} \nabla_M \xi^M$$



2D-diffeomorphisms (always)

$$\delta_\xi \mathcal{H}^{MN} = \mathcal{L}_\xi \mathcal{H}^{MN} = \xi^I \partial_I \mathcal{H}^{MN} + \mathcal{H}^{IN} \partial_I \xi^M + \mathcal{H}^{MI} \partial_I \xi^N$$

$$\delta_\xi e^{-2d} = \mathcal{L}_\xi e^{-2d} = \partial_I (\xi^I e^{-2d})$$

- ▶  $\left. \begin{matrix} e^{-2d} \\ \mathcal{R} \end{matrix} \right\}$  transform as  $\left\{ \begin{matrix} +1 \text{ density} \\ \text{scalar} \end{matrix} \right\}$  under gen. and 2D-diff.

## Flux formulation

[Geissbuhler, 2011, Aldazabal, Baron, Marques, and Nunez, 2011, Geissbuhler, Marques, Nunez, and Penas, 2013, ...]



Connect results to flux formulation of traditional DFT

1. introduce generalized vielbein  $\tilde{E}_{\hat{A}}^B$  for fluctuations with

$$\eta_{AB} = \tilde{E}^{\hat{C}}_A \tilde{E}^{\hat{D}}_B \eta_{\hat{C}\hat{D}} \quad \text{and} \quad \mathcal{H}_{AB} = \tilde{E}^{\hat{C}}_A \tilde{E}^{\hat{D}}_B \mathcal{S}_{\hat{C}\hat{D}}$$

2. combine it with background

$$\mathcal{E}_{\hat{A}}^I = \tilde{E}_{\hat{A}}^B E_B^I$$

3. find covariant fluxes
4. rewrite action



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absent in traditional DFT

$$\mathrm{O}(D) \times \mathrm{O}(D) \xleftarrow[\tilde{E}_{\hat{A}}^B]{\mathcal{H}_{AB}} \mathrm{O}(D, D) \xleftarrow[E_B^I]{\eta_{IJ}} \mathrm{GL}(2D)$$

## Covariant fluxes

- ▶ covariant flux in DFT

$$\mathcal{F}_{ABC} = (\mathcal{L}_{E_A} E_B^I) E_{CI}$$

$$\mathcal{F}_A = -(\mathcal{L}_{E_A} e^{-2d}) e^{2d}$$

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- covariant flux in DFT      and      in  $\text{DFT}_{\text{WZW}}$

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- ▶ scalars under generalized and  2D-diffeomorphisms
- ▶ split into background and fluctuation part, e.g.

$$\mathcal{F}_{\hat{A}\hat{B}\hat{C}} = F_{\hat{A}\hat{B}\hat{C}} + \tilde{F}_{\hat{A}\hat{B}\hat{C}}$$

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Jacobi identity  
full  $O(D, D)$  gaugings

$$F_{ABC} = 2\Omega_{[AB]C}$$

$$\Omega_{ABC} = D_A E_B^I E_{CI}$$

SC  
only  $GL(D) \times \Lambda_2 \subset O(D, D)$

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$$S = \int d^{2D} X e^{-2d} \left( S^{\hat{A}\hat{B}} \mathcal{F}_{\hat{A}} \mathcal{F}_{\hat{B}} + \frac{1}{4} \mathcal{F}_{\hat{A}\hat{C}\hat{D}} \mathcal{F}_{\hat{B}}^{\hat{C}\hat{D}} S^{\hat{A}\hat{B}} - \frac{1}{12} \mathcal{F}_{\hat{A}\hat{C}\hat{E}} \mathcal{F}_{\hat{B}\hat{D}\hat{F}} S^{\hat{A}\hat{B}} S^{\hat{C}\hat{D}} S^{\hat{E}\hat{F}} \right)$$

- ▶ looks like traditional flux formulation

**BUT** remember covariant fluxes are different

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**BUT** remember covariant fluxes are different
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- BUT** remember covariant fluxes are different
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- ▶ also invariant under double Lorentz transformations
- ▶ SC violating term  $\frac{1}{6} F_{\hat{A}\hat{B}\hat{C}} F^{\hat{A}\hat{B}\hat{C}}$  absent
- ✓ consistent with CFT with vanishing central charges

$$c_{\text{tot}} - \bar{c}_{\text{tot}} = \frac{\alpha'}{2} F_{\hat{A}\hat{C}\hat{B}} F^{\hat{A}\hat{B}\hat{C}} = 0$$

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- Questions:
- ✓ What are the covariant objects?
  - ▶ How is it connected to traditional DFT?

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  - ▶  $E_A{}^I \in \text{O}(D, D) \subset \text{GL}(2D)$
  - ▶ extended strong constraint

$$\partial_I b \partial^I f = 0$$

linking background fields  $b$  with fluctuations  $f$

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DFT  $\subset$  DFT<sub>WZW</sub>

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linking background fields  $b$  with fluctuations  $f$

both break  $2D$ -diffeomorphism invariance

# Scherk-Schwarz ansatz [Scherk and Schwarz, 1979, Geissbuhler, 2011, ...]

DFT

$$E_A^M = \hat{E}_A^N(\mathbb{X}) U_N^M(\mathbb{Y})$$

DFT<sub>WZW</sub>

$$\mathcal{E}_{\hat{A}}^M = \tilde{E}_{\hat{A}}^B(\mathbb{X}) E_B^M(\mathbb{Y})$$

DFT

$$E_A^M = \hat{E}_A^N(\mathbb{X}) U_N^M(\mathbb{Y})$$

$$U_N^M \in O(D, D)$$

strong constraint

$$F_{IJK} = 3U_{[I}^M \partial_M U_J^N U_{K]N}$$

DFT<sub>WZW</sub>

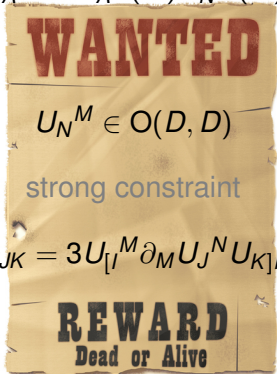
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–

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restrictions

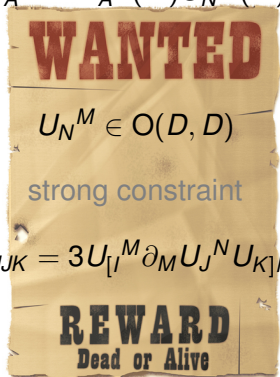
DFT	DFT <sub>WZW</sub>
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	<p>restrictions</p>
$U_N^M \in O(D, D)$ strong constraint	$E_B^M \in GL(2D)$ —
$F_{IJK} = 3U_{[I}^M \partial_M U_J^N U_{K]N}$	$F_{ABC} = 2E_{[A}^M \partial_M E_B]^N E_{CN}$

- ▶ no explicit construction of DFT twists for arbitrary embeddings



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- ▶ no explicit construction of DFT twists for arbitrary embeddings
- ▶ in DFT<sub>WZW</sub> one takes left invariant Maurer-Cartan form

## Summary

$\text{DFT}_{\text{WZW}}$  is a generalization of DFT

# DFT<sub>WZW</sub> is a generalization of DFT

- ▶ basic: idea go beyond the torus

**NEW!**

strong constraint, symmetries, action

**FREE**

genuinely non-geometric backgrounds and twist

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## Todo

- ▶ find solutions of the new strong constraint
- key to understand T-duality in DFT<sub>WZW</sub>
- ▶  $\alpha'$  corrections (here  $k^{-2}$ ,  $k^{-3}$ , ...) [Hohm, Siegel, and Zwiebach, 2013]
- ▶ coset and orbifold CFTs

Thank you for your attention. Are there any questions?

# Embedding tensor

ID	$M_{mn} / \cos \alpha$	$\tilde{M}^{mn} / \sin \alpha$	range of $\alpha$	gauging
1	diag(1, 1, 1, 1)	diag(1, 1, 1, 1)	$-\frac{\pi}{4} < \alpha \leq \frac{\pi}{4}$	$\begin{cases} \text{SO}(4), & \alpha \neq \frac{\pi}{4}, \\ \text{SO}(3), & \alpha = \frac{\pi}{4}. \end{cases}$
2	diag(1, 1, 1, -1)	diag(1, 1, 1, -1)	$-\frac{\pi}{4} < \alpha \leq \frac{\pi}{4}$	SO(3, 1)
	diag(1, 1, 1, 1)	diag(1, 1, 1, 1)	$-\frac{\pi}{4} < \alpha \leq \frac{\pi}{4}$	SO(2, 2), $\alpha \neq \frac{\pi}{4}$ ,

[Dibitetto, Fernandez-Melgarejo, Marques, and Roest, 2012]

## ► fluxes for embedding one

$$F_{abc} = \sqrt{2}\epsilon_{abc}(\cos \alpha + \sin \alpha) \quad \text{and} \quad F_{\bar{a}\bar{b}\bar{c}} = \sqrt{2}\epsilon_{abc}(\cos \alpha - \sin \alpha)$$

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- ▶ DFT strong constraint holds only for

$$F_{ABC}F^{ABC} = 6 \sin(2\alpha) = 0 \quad \rightarrow \quad \alpha = \frac{\pi}{2}n \quad n \in \mathbb{Z}$$

- ▶ Jacobi identity holds always