

Generalized Geometry of α' -corrections

Falk Hassler

Based on 2409.00176, 2412.17893 and 2412.17900 with

Daniel Butter, Achilles Gitsis,
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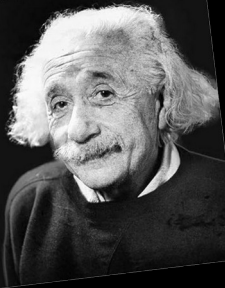
The Problem

- Einstein-Hilbert action is not renormalizable in $d > 2$ \longrightarrow only EFT

$$S = \int dx^d \sqrt{-g} (R + a_1 R^2 + a_2 R_{ij} R^{ij} + \dots)$$

Do not worry about
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ALBERT EINSTEIN



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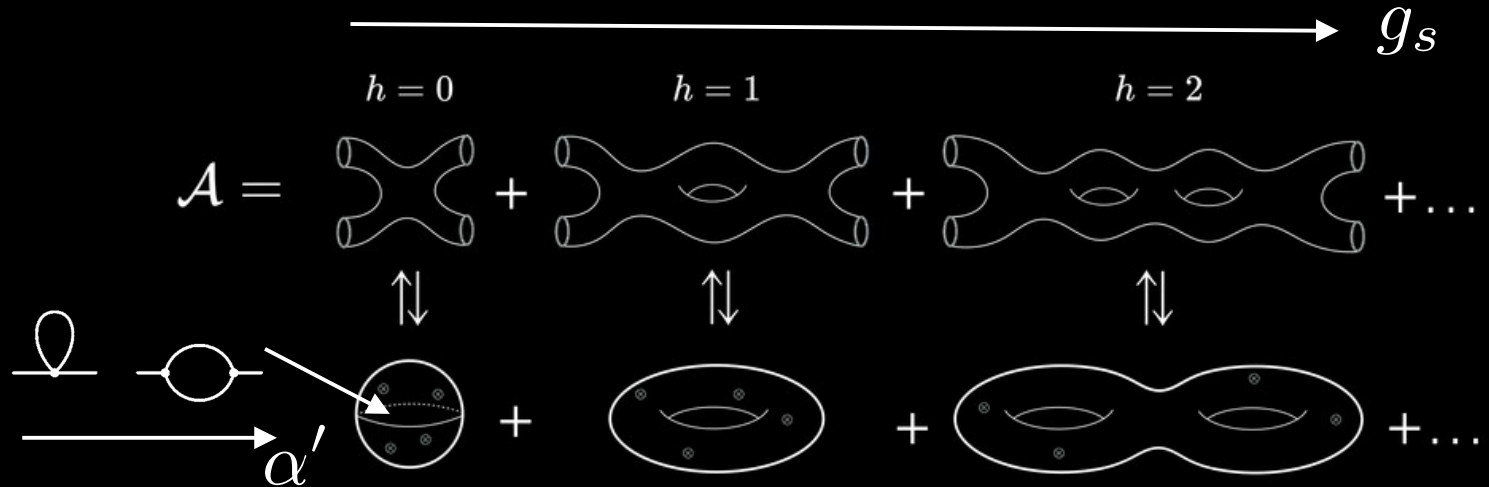
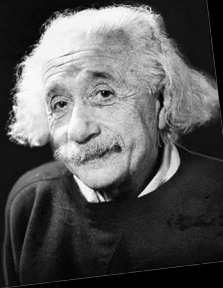
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Question: How do we obtain all the coefficients ?

String Theory

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NS/NS-sector @ leading order in α'

$$S = \int dx^d \sqrt{-g} e^{-2\phi} \left(R + 4(\partial\phi)^2 - \frac{1}{12} \tilde{H}^2 + \frac{a}{8} R_{ija}^{(-)b} R^{(-)ij}{}_b{}^a + \frac{b}{8} R_{ija}^{(+b)} R^{(+ij)}{}_b{}^a + \dots \right)$$

$\tilde{H}_{ijk} = H_{ijk} - \frac{3}{2}a\Omega_{ijk}^{(-)} + \frac{3}{2}b\Omega_{ijk}^{(+)}$

$a = -\alpha, b = 0$	heterotic
$a = b = -\alpha'$	bosonic
$a = b = 0$	type II

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- 3 coefficients for terms with 2
 - 8 coefficients for terms with 4
 - 60 coefficients for terms with 6
- } derivatives

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Too many terms. Nothing is known about > 8 derivatives.

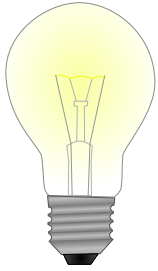


A better approach:

Leverage symmetry to decrease number of possible terms.

Like diffeomorphisms, gauge-transformations and:

- SUSY
- Extended Generalized Lorentz Symmetry (today)
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generalized frame

$$E_A^I = \begin{pmatrix} e_a^i & e_a^j B_{ji} \\ 0 & e^a_i \end{pmatrix}$$

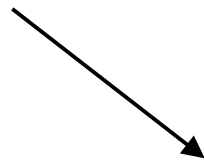


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invariant under $O(d) \times O(d) \subset O(d, d)$

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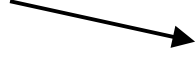
$$\eta_{AB} = \begin{pmatrix} 0 & \delta_{\alpha}^{\beta} \\ \delta_{\beta}^{\alpha} & 0 \end{pmatrix} \quad \mathbb{H}_{AB} = \begin{pmatrix} \delta_{ab} & 0 \\ 0 & \delta^{ab} \end{pmatrix}$$

Leading Symmetries and Action

$$\delta E^A_M = \mathbb{L}_\xi E^A_M + \Lambda^A_B E^B_M, \quad \Lambda^A_B \in O(d) \times O(d)$$



generalized Lie derivative



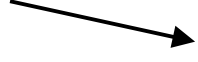
generalized Lorentz transformation

- 1) diffeomorphisms (gravity)
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transformation of fermions

generalized flux $F_{ABC} = 3D_{[A} E_B^I E_{C]I}$ with $D_A = E_A^i \partial_i$

$$F_A = D_A d - \partial_i E_A^i \quad d = -\frac{1}{2} \log(-g) + \phi$$

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$$F_A = D_A d - \partial_i E_A^i \quad d = -\frac{1}{2} \log(-g) + \phi$$

$$S = \int dx^d e^{-2d} \mathcal{R}$$

one unique invariant

$$\mathcal{R}(F_{ABC}, F_A, D_A, H_{AB})$$

We need a Factory for Invariants...

Symmetries

- gen. diff
- gen. Lorentz



Generalized Cartan Geometry*

Invariants

\mathcal{R}, \dots

[Polacek, Siegel 13;
Butter 21;
Butter, FH, Pope, Zhang 23]

*) also known as Poláček-Siegel construction, or for mathematicians: symplectic reduction of Courant algebroids

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Covariant derivative:

$$\nabla_A E_B^M = E_A^N \partial_N E_B^M + \Omega_{AB}^C E_C^M - E_A^N \Gamma_{NL}^M E_B^L$$

gen. spin and affine connection, related by

$$\nabla_A E_B^M = 0$$

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R_{ABC}^D & T_{AB}^C

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Solution: Poláček-Siegel constr.

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2 connections are required: $\Omega_A^\alpha, \rho^{\alpha\beta}$ ← adjoint index of the gen. Lorentz group G_S

$\Omega_A^\alpha, \rho^{\alpha\beta}, E_A^I$ parameterize a mega-frame $\mathcal{E}_A^I \in G_{PS}$

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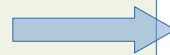


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$$O(d+n, d+n) \rightarrow O(d, d) \times G_S, n = \dim(G_S)$$

$$\cup \\ G_{PS} \supset G_S$$



= Generalized Cartan Geometry



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Cartan connection $\theta(x) : T_x P \rightarrow \mathfrak{g}$

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$$\theta = t_{\hat{a}} \theta^{\hat{a}}_{\hat{i}} dx^{\hat{i}}$$

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Cartan curvature

$$\Theta = -d\theta + \frac{1}{2} [\theta, \theta]$$

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Generalized Cartan curvature

$$\Theta_{\hat{A}\hat{B}} = -[\theta_{\hat{A}}, \theta_{\hat{B}}]_{\mathfrak{D}, \mathfrak{D}}$$

\mathfrak{D} -twisted Dorfman-bracket

Choosing G_S and G_{PS}

Objective:

1) fix all connections by

1) gauge fixing

2) torsion constraints

in terms of the generalized frame (and its derivatives)

2) as few invariants as possible

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$$G_S = O(d + p) \times O(d + q)$$

$$G_{PS} = O(d + p, d + q)$$

G_{PS} in more detail

- we split the generators into

$$O(d, d) \subset G_{\text{PS}}$$

$$\mathcal{K}_{AB} = \begin{pmatrix} K_{AB} & -\frac{1}{2}R_A^\beta \\ \frac{1}{2}R_B^\alpha & -\frac{1}{2}R^{\alpha\beta} \end{pmatrix}$$

which are governed by

$$[\mathcal{K}_{AB}, \mathcal{K}_{CD}] = 2\eta_{[A|[C\mathcal{K}_D]|B]}$$

with

$$\eta_{AB} = \begin{pmatrix} \eta_{AB} & 0 \\ 0 & \kappa^{\alpha\beta} \end{pmatrix}$$

- we also need

structure coefficients of G_{S}

$$R_\alpha = \frac{1}{2}f_{\alpha\beta}{}^\gamma \kappa^{\beta\delta} R_{\gamma\delta}$$

Recursive embedding of G_S

- G_{PS} is generated by $K_{AB}, R_{\alpha}^A, R_{\alpha\beta}$
 - and G_S by $\tau_{\alpha} = (\tau_{\bar{\alpha}} \quad \tau_{\underline{\alpha}})$
- How to relate them ???
- left and right factors of G_S

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- exponential growth of generators

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- exponential growth of generators
- can be truncated at every order

A game of splitting indices

$$[\tau_{\underline{\alpha}}, \tau_{\underline{\beta}}] = -f_{\underline{\alpha}\underline{\beta}}^{\underline{\gamma}} \tau_{\underline{\gamma}}$$

$$[\tau_{\underline{\alpha}_I \underline{\beta}_J}, \tau_{\underline{\gamma}_K \underline{\delta}_L}] = 2g_{\underline{\quad}} \eta_{[\underline{\alpha}_I | [\underline{\gamma}_K \tau_{\underline{\delta}_L}] | \underline{\beta}_J]}$$

$$\frac{1}{g_{\underline{\quad}}^2} \langle\langle \tau_{\underline{\alpha}_I \underline{\beta}_J}, \tau_{\underline{\gamma}_K \underline{\delta}_L} \rangle\rangle = \eta_{[\underline{\alpha}_I | [\underline{\gamma}_K \eta_{\underline{\delta}_L}] | \underline{\beta}_J]} = \kappa_{\underline{\alpha}_I \underline{\beta}_J \underline{\gamma}_K \underline{\delta}_L}$$

Example: $\kappa_{\underline{\alpha}_1 \underline{\beta}_1} = \kappa_{\underline{\alpha}_1 \underline{\alpha}_2 \underline{\beta}_1 \underline{\beta}_2} = \eta_{[\underline{\alpha}_1 | [\underline{\beta}_1 \eta_{\underline{\beta}_2}] | \underline{\alpha}_2]}$

Torsion constraints and gauge fixing

- Poláček-Siegel construction results one quantity (product):

The generalized Cartan curvature Θ_{ABC} ← fundamental index of G_{PS}

- Remember, it contains all curvatures and torsions of the gen. connections

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- To fix them completely, we impose:

$$\Theta_{\underline{ABC}} = \Theta_{\overline{ABC}} = 0$$

Torsion constraint

$$\Omega_{\underline{a}}^{\overline{\alpha}} = \Omega_{\underline{a}}^{\underline{\alpha}} = \rho^{\overline{\alpha}\overline{\beta}} = \rho^{\underline{\alpha}\underline{\beta}} = 0$$

Gauge fixing of chiral/anti-chiral sector

Torsion constraints

$$\mathcal{A}_A^{(l)\beta} \tau_\beta \cong -\mathcal{F}_A^{(l)} = \mathcal{A}_A^{(l)\beta} R_\beta - \mathcal{F}_A^{(l)} [A^{(<l)}]$$

$$\mathcal{F}_A = \langle \mathcal{A} | \mathcal{A} |^B \rangle (D_B \mathcal{A} \mathcal{A}^{-1} + \mathcal{A} F_B \mathcal{A}^{-1}) - \langle \mathcal{A} | \mathcal{A} |_\beta \rangle \mathcal{A} R^\beta \mathcal{A}^{-1} + \langle \mathcal{A} | D_B \mathcal{A} \mathcal{A}^{-1} \mathcal{Z} \mathcal{A} |^B \rangle$$

$$\mathcal{A} = \exp (A + c_3 A^3 + c_5 A^5 + \dots)$$

$$F_A = F_{ABC} K^{BC}$$

fixed by torsion constraints

Collapsing towers

The real identification is

$$\begin{array}{c} \mathcal{A}_{\mathcal{A}}^{(l)\beta} t_{\beta} \cong -\mathcal{F}_{\mathcal{A}}^{(l)} [A^{(<l)}] \\ \downarrow \\ \tau_{\alpha} = t_{\alpha} + R_{\alpha} \end{array}$$

similarity transformation required $t_{\underline{\alpha}} = S_{\underline{\alpha}}^{\beta} \tau_{\underline{\beta}}$

and we have to compute $\tilde{\kappa}_{\alpha\beta} := (S^{-1})_{\underline{\alpha}}^{\gamma} \kappa_{\underline{\gamma}\underline{\delta}} (S^{-1})_{\underline{\beta}}^{\delta}$

$$\tilde{f}_{\underline{\alpha}\underline{\beta}\underline{\gamma}} := (S^{-1})_{\underline{\alpha}}^{\delta} (S^{-1})_{\underline{\beta}}^{\epsilon} (S^{-1})_{\underline{\gamma}}^{\rho} f_{\underline{\delta}\underline{\epsilon}\underline{\rho}}$$



Solutions for torsion constraints

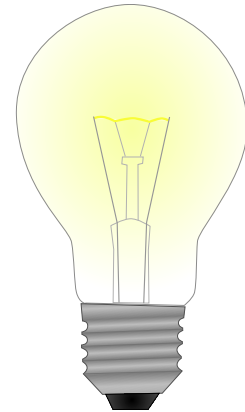
for convenience we define $\tilde{A}_{\mathcal{A}}^{(l)\beta} \tau_{\beta} = A_{\mathcal{A}}^{(l)\beta} t_{\beta}$ to get

$$\tilde{A}_{\underline{a}\beta_{\underline{1}}}^{(1)} = \tilde{A}_{\underline{a}}^{(1)\underline{b}_1\underline{b}_2} = -\frac{1}{g_-} F_{\underline{a}}^{\underline{b}_1\underline{b}_2}$$

$$\tilde{A}_{\underline{a}}^{(2)\underline{b}}_{\underline{\beta}} = \frac{1}{g_-} \left(F_{\underline{a}}^{\underline{b}\bar{c}} A_{\underline{c}\underline{\beta}}^{(1)} + D^{\underline{b}} A_{\underline{a}\underline{\beta}}^{(1)} \right)$$

$$\tilde{A}_{\underline{\alpha}}^{(2)\underline{b}_1\underline{b}_2} = -\frac{1}{g_-} \left(2D^{[\underline{b}_1} A^{(1)\underline{b}_2]}_{\underline{\alpha}} - A^{(1)\underline{a}}_{\underline{\alpha}} F_{\underline{a}}^{\underline{b}_1\underline{b}_2} - \right. \\ \left. A^{(1)\underline{b}_1\bar{\beta}} A^{(1)\underline{b}_2\bar{\gamma}} f_{\underline{\alpha}\bar{\beta}\bar{\gamma}} \right)$$

Linus' and Stan's
"generalized Riemann tensor"



Gauge fixing

objective: preserve

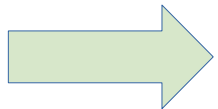
$$\Omega_{\bar{a}}^{\bar{\alpha}} = \Omega_{\underline{a}}^{\underline{\alpha}} = \rho^{\bar{\alpha}\bar{\beta}} = \rho^{\underline{\alpha}\underline{\beta}} = 0$$

under gauge transformations

Gauge fixing of chiral/anti-chiral sector

$$\delta A^{(l)} + \delta E^{(l)} E^{-1} + \dots = \xi^{(l)\alpha} t_{\alpha} + \dots$$

depend on lower orders already fixed



allows to fix $\delta A^{(l)}, \delta E^{(l)}, \xi^{(l)}$

Universal gen. GS transformations

$$\delta E_{\underline{a}\bar{b}}^{(2m)} = A_{\underline{a}\bar{\alpha}} D_{\bar{b}} \xi^{\bar{\alpha}} - \text{c.c.} \Big|^{(2m)}$$

*) TODO:

- collapsing the towers
- inserting previous solutions from torsion constraints & gauge fixing

$$\begin{aligned} \delta E_{\underline{a}\bar{b}}^{(4)} = & \bar{\chi} \tilde{A}_{\underline{a}\bar{\alpha}_1}^{(3)} D_{\bar{b}} \tilde{\xi}^{(0)\bar{\alpha}_1} + \bar{\chi} \tilde{A}_{\underline{a}\bar{\alpha}}^{(2)} D_{\bar{b}} \tilde{\xi}^{(1)\bar{\alpha}} + \bar{\chi} \tilde{A}_{\underline{a}\bar{\alpha}_1}^{(1)} D_{\bar{b}} \tilde{\xi}^{(2)\bar{\alpha}_1} + \\ & \bar{\chi}_1 \tilde{A}_{\underline{a}\bar{\alpha}}^{(3)} D_{\bar{b}} \tilde{\xi}^{(0)\bar{\beta}_1} (\tilde{S}^{-1})_{\bar{\beta}_1}^{\bar{\alpha}} + \bar{\chi} \tilde{A}_{\underline{a}}^{(1)\bar{\alpha}_1} D_{\bar{b}} \tilde{\xi}_{\bar{\beta}}^{(2)} (\tilde{S}^{-1})_{\bar{\alpha}_1}^{\bar{\beta}} - \text{c.c.} . \end{aligned}$$

...and again

$$\begin{aligned}
 \delta E_{\underline{a}\bar{b}}^{(4)} = & -\frac{a^2}{2} \left[D_{\underline{a}} D_{\underline{c}} \Lambda_{\underline{de}} \left(F_{\underline{fb}}^{\underline{c}} F^{\bar{f}de} + D^{\underline{c}} F_{\underline{b}}^{\underline{de}} \right) - F_{\underline{bf}}^{\underline{g}} F^{\bar{c}}_{\underline{dg}} \left(F_{\underline{c}}^{\underline{ed}} D_{\underline{a}} \Lambda_{\underline{e}}^{\underline{f}} - F_{\underline{c}}^{\underline{ef}} D_{\underline{a}} \Lambda_{\underline{e}}^{\underline{d}} \right) \right. \\
 & \left. + D_{\underline{a}} \Lambda_{\underline{ef}} F^{\bar{c}\underline{e}}_{\underline{d}} \left(F_{\underline{bcg}} F^{\bar{g}fd} - D_{\underline{b}} F_{\underline{c}}^{\underline{fd}} + 2D_{\underline{c}} F_{\underline{b}}^{\underline{fd}} \right) + F_{\underline{b}}^{\underline{ed}} D_{\underline{a}} \left(D^{\bar{c}} \Lambda_{\underline{e}}^{\underline{f}} F_{\underline{cfd}} \right) \right] \\
 & -\frac{ab}{4} \left[D_{\underline{a}} \Lambda^{\underline{cd}} \left(F_{\underline{bcg}} F^{\bar{g}\underline{e}\bar{f}} F_{\underline{de}\bar{f}} - D_{\underline{b}} F_{\underline{c}}^{\bar{e}\bar{f}} F_{\underline{de}\bar{f}} \right) + F_{\underline{bcd}} D_{\underline{a}} \left(D^{\underline{c}} \Lambda_{\underline{e}\bar{f}} F^{\underline{de}\bar{f}} \right) \right. \\
 & \left. - D_{\underline{b}} \Lambda^{\bar{c}\underline{d}} \left(F_{\underline{acg}} F^{\bar{g}\underline{e}\bar{f}} F_{\underline{de}\bar{f}} - D_{\underline{a}} F_{\underline{c}}^{\underline{ef}} F_{\underline{de}\bar{f}} \right) - F_{\underline{acd}} D_{\underline{b}} \left(D^{\bar{c}} \Lambda_{\underline{e}\bar{f}} F^{\underline{de}\bar{f}} \right) \right] \\
 & +\frac{b^2}{2} \left[D_{\underline{b}} D_{\underline{c}} \Lambda_{\underline{de}} \left(F_{\underline{fa}}^{\bar{c}} F^{\underline{fde}} + D^{\bar{c}} F_{\underline{a}}^{\underline{de}} \right) - F_{\underline{af}}^{\bar{g}} F^{\underline{c}}_{\underline{dg}} \left(F_{\underline{c}}^{\bar{e}\underline{d}} D_{\underline{b}} \Lambda_{\underline{e}}^{\bar{f}} - F_{\underline{c}}^{\bar{e}\bar{f}} D_{\underline{b}} \Lambda_{\underline{e}}^{\bar{d}} \right) \right. \\
 & \left. + D_{\underline{b}} \Lambda_{\underline{e}\bar{f}} F^{\bar{c}\underline{e}}_{\underline{d}} \left(F_{\underline{acg}} F^{\bar{g}fd} - D_{\underline{a}} F_{\underline{c}}^{\bar{f}d} + 2D_{\underline{c}} F_{\underline{a}}^{\bar{f}d} \right) + F_{\underline{a}}^{\bar{e}\underline{d}} D_{\underline{b}} \left(D^{\underline{c}} \Lambda_{\underline{e}}^{\bar{f}} F_{\underline{cfd}} \right) \right]
 \end{aligned}$$



matches [Baron, Marques 20]

Remarks

- requires a particular prescription of “collapsing the towers”
- for other “regularizations” residual transformations will not close
- invariant action follows from the mega-space (=standard two derivative action there)

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There is a hidden symmetry in string theory which controls higher-derivative(α')-corrections. How far can we push it?